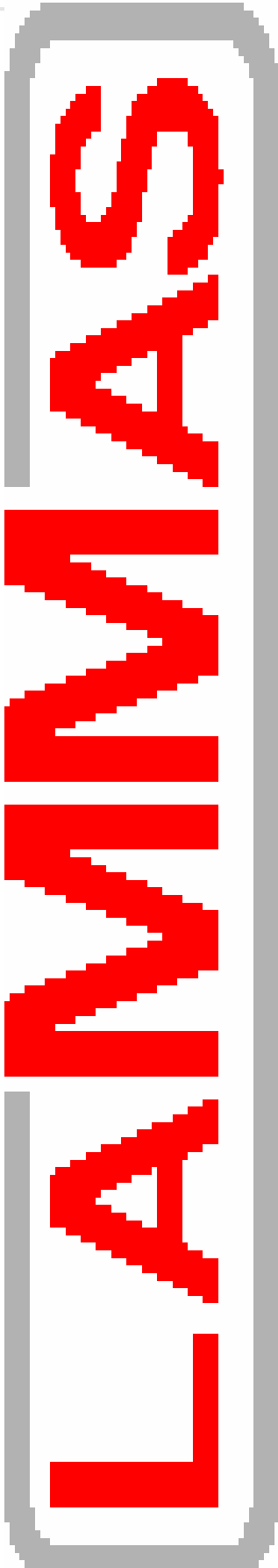


PRESS-FIT SYSTEM



PRESS-FIT SYSTEM CONFIGURATION

CONTROL UNIT

- Power module for press spindle
- Positioning and force control and monitor
- Management of press-fit process
-

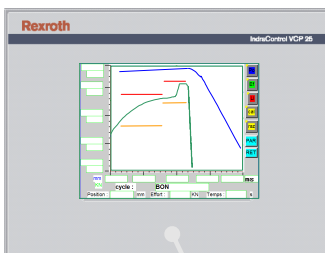
INTERCHANGES WITH PLC

Current available interface channels with other remote control units are the followings:

- Parallel interface
- PROFIBUS-DP
- CAN_OPEN
- DEVICENET
- PROFINET

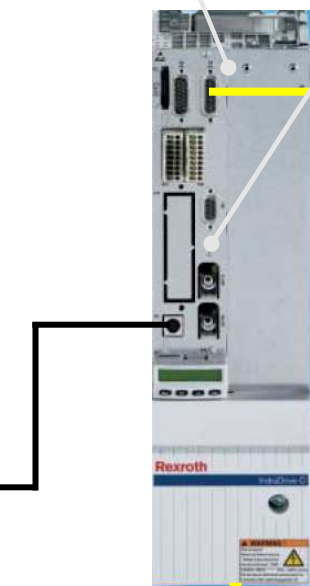
MOTOR

- Brushless synchronous motor with absolute encoder
- Positioning accuracy 0,01mm



DIGITAL INTERFACE HMI

- Setting of application parameters
- Display in tabular form the process results of force-position curve
- Traceability
- Print stored data of the press-fit processes
- ...



REDUCTION GEAR

- Planetary gearbox

FORCE MEASURING

- Integrated load cell
- Measuring accuracy <0,5%



SPINDLE

- Planetary recirculating roller screw
- Splined shaft with 6 grooves driven by a ball spline nut

CARACTERISTIQUES MAIN CLAUSES OF LAMMAS PRESS

- ✓ Coaxiality of then motor, gearbox and spindle
- ✓ The planetary roller screw allows to work with heavy loads and severe conditions, thanks to the presence of no. 4 angular contact ball bearings mounted in opposition to each other to support loads on the two directions.
- ✓ The spindle that consists of a splined shaft driven by a ball spline nut.

PRODUCTS AND PERFORMANCES

PRESS-FIT CODES

LAMMAS code	Nominal force (KN)	Max. stroke (mm)
PL 0030 0150	30	150
PL 0030 0250	30	250
PL 0060 0150	60	150
PL 0060 0250	60	250
PL 0080 0150	80	150
PL 0080 0250	80	250
PL 0120 0150	120	150
PL 0120 0250	120	250
PL 0200 0150	200	150
PL 0200 0250	200	250

LAMMAS is available to evaluate the feasibility of presses with different powers of strokes, from those listed in the table, based on the technical data of the requested application.

Press composition :

- Press spindle
- Brushless synchronous motor with absolute encoder and cable kit
- Planetary gearbox
- Load cell, signal amplifier and cable set
- Digital operator interface
- Basic software for process data management and back-up

ADVANTAGES OF USING PRESS-FIT

	Electrical press LAMMAS	Press with hydraulic cylinder
Positioning	Very easy, adjustable by loading and positioning data set	Complicated, few settings allowed
Speed	Very high, modifiable	Middle, fixed
Rigidity of the body	Compact and very high	Middle
Efficiency	>90%	<50%
Installation and starting up	Simple, speedy and modifiable	Complexity of the hydraulic system
Maintenance	Practically maintenance free	Many adjustments and calibrations to be repeated
Environmental conditions	Silent, and no pollutant	Risk of oil leakage, noisy

REQUESTED APPLICATIONS

- Pressing
- Seaming, riveting
- Coupling
- Drawing of iron sheet
- Assembling
-

REFERENCES

Renault, Peugeot, Citroen, Bentler, Mécachrome, Volvo...

INTERFACE PARAMETER MENU

PRESS-FIT: 6 Tonn LAMMAS ELOGIA

State speed drive : A4002 DRIVE in automatic mode

Program in progress : 03
 Phase in progress : 05
 Position in progress : 26.02 mm
 Current load: 30.00 KN

Last memorized values :
 Cycle : GOOD

Position: 25.08mm Load: 29.99 kN Time: 0.750 s

DATA CURVES TRACEABILITY MANUAL PARAMETERS

Press working

MANUAL MODE 23.11.05 13:55:34

PROGRAM N° 11
 PHASE N° 05 **START** **STOP**

Position in progress : 72.00 mm
 Current load: 30.00 KN

Last memorized values :
 Cycle : GOOD

Position : 74.00 mm Load : 30.99 KN Time : 0.750 s

ERROR CODE : **ERROR DISPLAY**

OPTIONS **PREVIOUS**

PRESS WORKING

PROGRAM INPUT 23.11.05 13:55:34

Prg : 11 EXAMPLE PHASE N° 15

1	QUICK APPROACH	
2	SLOW APPROACH	
3	PRESS FITTING	
4	SETTLING	-
5	QUICK RETURN	
6	.	
7	.	
8	.	
9	.	
10	.	

SETTLING **ENTER** **DELETE** **ADD**

Nbr phases : 05 **PREVIOUS**

PRESS WORKING

PHASE DATA INPUT 23.11.05 13:55:34

Phase : 04 **SETTLING** **VAR**

Speed : 7200 mm/min Displacement Abs /rel **ABS** Shut down

Position : 04.99 mm YES

Load : 40.00 KN Limit current : WITHOUT % NO

Time : 0.401 s NO

End program on phase : NO Memo phases values : NO

Sequence movement : NO without/with deceleration **WITHOUT**

Trigger recording : NO Time base : ms

Position control : WITHOUT min mm max mm

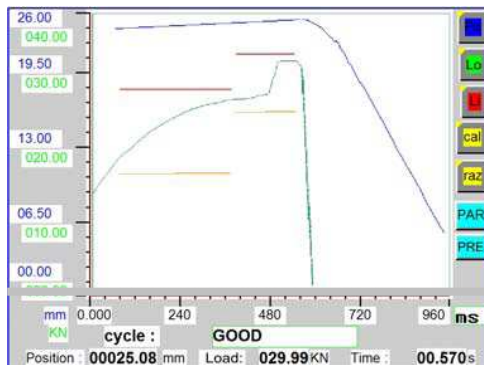
Load control : WITHOUT min KN max KN

Time control : WITHOUT max s

Stop programs on defect : NO

Load control : **END** **PREVIOUS**

PRESS WORKING



100 LAST END VALUES 23.11.05 13:55:34

Value	Position	Load	Time	date	hour
Value : 10 =	50.00	00.40	0.750	23 11 05	13 54 05
Value : 11 =	75.00	20.00	1.200	23 11 05	13 54 00
Value : 12 =					
Value : 13 =					
Value : 14 =					
Value : 15 =					
Value : 16 =					
Value : 17 =					
Value : 18 =					
Value : 19 =					

PREVIOUS

Press working

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